

PIC863Mercury Tango Cpp Class

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PIC863Mercury Class Identification :

Contact : at mail.desy.de - tnunez
Class Family : Motion
Platform : Unix Like
Bus : Socket
Manufacturer : PI
Manufacturer ref. : C863

PIC863Mercury Class Inheritance :

- [Tango::DeviceImpl](#)
 - PIC863Mercury

PIC863Mercury Class Description :

Class for controlling motors using the C-863.10 Mercury DC Motor Controller from PI.

PIC863Mercury Properties :

There is no class properties

Device Properties			
Name	Description	Type	Default Value
SocketDS	Name of the tango device making the connection to the terminal server.	String	none
CtrlID	Id of the controller: 0 -> ascii 48, 1 -> ascii 49, 2 ascii 50	int	0

PIC863Mercury Class Commands				
Name	Input type	Output type	Level	Description
State	DEV_VOID	DEV_STATE	OPERATOR	This command gets the device state (stored in its device_state data member) and returns it to the caller.
Status	DEV_VOID	CONST_DEV_STRING	OPERATOR	This command gets the device status (stored in its device_status data member) and returns it to the caller.
StopMove	DEV_VOID	DEV_VOID	OPERATOR	None.
Calibrate	DEV_DOUBLE	DEV_VOID	OPERATOR	Only for compatibility reasons. Does nothing.
ResetMotor	DEV_VOID	DEV_VOID	OPERATOR	Only for compatibility. It does nothing.

Command State :

This command gets the device state (stored in its device_state data member) and returns it to the caller.

State Definition		
Input Argument	Tango::DEV_VOID	none
Output Argument	Tango::DEV_STATE	Device state
DisplayLevel	OPERATOR	..
Inherited	true	..
Abstract	false	..
Polling Period	Not polled	..

Command allowed for All states ..

Command Status :

This command gets the device status (stored in its device_status data member) and returns it to the caller.

Status Definition		
Input Argument	Tango::DEV_VOID	none
Output Argument	Tango::CONST_DEV_STRING	Device status
DisplayLevel	OPERATOR	..
Inherited	true	..
Abstract	true	..
Polling Period	Not polled	..
Command allowed for	All states	..

Command StopMove :

StopMove Definition		
Input Argument	Tango::DEV_VOID	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..
Abstract	false	..
Polling Period	Not polled	..
Command allowed for	All states	..

Command Calibrate :

Only for compatibility reasons. Does nothing.

Calibrate Definition		
Input Argument	Tango::DEV_DOUBLE	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..
Abstract	false	..
Polling Period	Not polled	..
Command allowed for	All states	..

Command ResetMotor :

Only for compatibility. It does nothing.

ResetMotor Definition		
Input Argument	Tango::DEV_VOID	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..
Abstract	false	..
Polling Period	Not polled	..
Command allowed for	All states	..

PIC863Mercury Class Attributes							
Name	Inherited	Abstract	Attr. type	R/W type	Data type	Level	Description
Position	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	
UnitLimitMin	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	
UnitLimitMax	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	

SlewRate	false	false	Scalar	READ_WRITE	Tango::DEV_LONG	OPERATOR	
Acceleration	false	false	Scalar	READ_WRITE	Tango::DEV_LONG	OPERATOR	
Conversion	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	Conversion factor: steps = conversion*units

There is no dynamic attribute defined.

Attribute Position :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	Not set
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	mm
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute UnitLimitMin :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	mm
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute UnitLimitMax :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false

Attribute Properties	
label	
unit	mm
standard unit	
display unit	
format	
max_value	
min_value	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set

Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute SlewRate :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_LONG
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	Not set
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	counts/s
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute Acceleration :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_LONG
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	Not set
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	counts/s^2
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute Conversion :

Conversion factor: steps = conversion*units

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE

Attribute Properties	
label	
unit	steps/mm
standard unit	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set

Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

PIC863Mercury Class States	
Name	Description
ON	
MOVING	
FAULT	