

MonoUndSynchronMotor Tango Python Class

Contents :

- [Description](#)
- [Properties](#)
- [Commands](#)
 - [State](#)
 - [Status](#)
 - [Calibrate](#)
 - [StopMove](#)
 - [ResetMotor](#)
- [Attributes](#)
 - [Position](#)
 - [UndOffset](#)
 - [FeedbackTime](#)
 - [UnitLimitMin](#)
 - [UnitLimitMax](#)
 - [MoveTime](#)
- [States](#)

MonoUndSynchronMotor Class Identification MonoUndSynchronMotor Class Inheritance

<p>⋮</p> <p>Contact : at mail.desy.de - tnunez</p> <p>Class Family : Motion</p> <p>Platform : Unix Like</p> <p>Bus : Not Applicable</p> <p>Manufacturer : none</p> <p>Manufacturer ref. :</p>	<p>⋮</p> <ul style="list-style-type: none"> ○ Tango::DeviceImpl <ul style="list-style-type: none"> ■ MonoUndSynchronMotor
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MonoUndSynchronMotor Class Description :

Class performing synchronized monochromator and undulator movements.
Undulator slewrate is adjusted during the movement.

MonoUndSynchronMotor Properties :

There is no class properties

Device Properties			
Name	Description	Type	Default Value
MonoDevice	Name of the monochromator Tango device	String	none
UndDevice	Name of the undulator Tango device	String	none

MonoUndSynchronMotor Class Commands				
Name	Input type	Output type	Level	Description
State	DEV_VOID	DEV_STATE	OPERATOR	This command gets the device state (stored in its <i>device_state</i> data member) and returns it to the caller.
Status	DEV_VOID	CONST_DEV_STRING	OPERATOR	This command gets the device status (stored in its <i>device_status</i> data member) and returns it to the caller.
Calibrate	DEV_DOUBLE	DEV_VOID	OPERATOR	None.
StopMove	DEV_VOID	DEV_VOID	OPERATOR	None.
ResetMotor	DEV_VOID	DEV_VOID	OPERATOR	None.

Command State :

This command gets the device state (stored in its *device_state* data member) and returns it to the caller.

State Definition		
Input Argument	Tango::DEV_VOID	none.
Output Argument	Tango::DEV_STATE	State Code
DisplayLevel	OPERATOR	..
Inherited	true	..
Abstract	true	..
Polling Period	Not polled	..

Command allowed for	All states	..
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Command Status :

This command gets the device status (stored in its *device_status* data member) and returns it to the caller.

Status Definition		
Input Argument	Tango::DEV_VOID	none.
Output Argument	Tango::CONST_DEV_STRING	Status description
DisplayLevel	OPERATOR	..
Inherited	true	..
Abstract	true	..
Polling Period	Not polled	..
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Command allowed for	All states	..

Command Calibrate :

Calibrate Definition		
Input Argument	Tango::DEV_DOUBLE	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..
Abstract	false	..
Polling Period	Not polled	..
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Command allowed for	All states	..

Command StopMove :

StopMove Definition		
Input Argument	Tango::DEV_VOID	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..
Abstract	false	..
Polling Period	Not polled	..
Command allowed for	All states	..

Command ResetMotor :

ResetMotor Definition		
Input Argument	Tango::DEV_VOID	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..
Abstract	false	..
Polling Period	Not polled	..
Command allowed for	All states	..

MonoUndSynchronMotor Class Attributes							
Name	Inherited	Abstract	Attr. type	R/W type	Data type	Level	Description
Position	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	
UndOffset	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	Offset between undulator and monochromator

							energy
FeedbackTime	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	Time between undulator velocity controls
UnitLimitMin	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	
UnitLimitMax	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	
MoveTime	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	Move time if the motors are fast enough. The time needed by the slowest motor will be used in other case.

There is no dynamic attribute defined.

Attribute Position :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	Not set
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	eV
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false

Push DataReady event by user code	Not set
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Attribute UndOffset :

Offset between undulator and monochromator energy

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	eV
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	Not set

Attribute FeedbackTime :

Time between undulator velocity controls

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	s
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	Not set

Attribute UnitLimitMin :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set

Read allowed for	All states
Write allowed for	All states

min_warning	
delta_time	
delta_val	

Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	Not set

Attribute UnitLimitMax :

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	Not set

Attribute MoveTime :

Move time if the motors are fast enough. The time needed by the slowest motor will be used in other case.

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	s
standard unit	
display unit	
format	
max_value	
min_value	0
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	Not set

MonoUndSynchronMotor Class States	
Name	Description
ON	
MOVING	