

PIDController Tango Python Class

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PIDController Class Identification :

Contact : at mail.desy.de - tnunez
Class Family : BeamDiagnostics
Platform : Unix Like
Bus : Not Applicable
Manufacturer : none
Manufacturer ref. :

PIDController Class Inheritance :

- [Tango::DeviceImpl](#)
 - PIDController

PIDController Class Description :

Class for controlling a variable using the PID algorithm

PIDController Properties :

There is no class properties

Device Properties			
Name	Description	Type	Default Value
InputDS	Device Server where the input parameters are read from	String	None
OutputDS	Device Server where the output parameter is write to	String	None
InputValueLogic	String describing what to read from the input device and possible operations: 0 -> read value 1 -> difference of average values Format, ex. 0,AttrbuteName (read attribute AttributeName from InputDS and used as input value) 1,Attr1,Attr2,Attr3,Attr4 (read Attr1 ,Attr2 ,Attr3 and Attr4 form InputDS and use (Attr1+Attr) - (Attr3+Attr4) as input value More logics can be implemented.	String	none
OutputAttribute	Name of the attribute for writing the pid computed value.	String	none

PIDController Class Commands				
Name	Input type	Output type	Level	Description
State	DEV_VOID	DEV_STATE	OPERATOR	This command gets the device state (stored in its device_state data member) and returns it to the caller.
Status	DEV_VOID	CONST_DEV_STRING	OPERATOR	This command gets the device status (stored in its device_status data member) and returns it to the caller.
StartCtrlLoop	DEV_VOID	DEV_VOID	OPERATOR	Start control loop
StopCtrlLoop	DEV_VOID	DEV_VOID	OPERATOR	Stop control loop

Command State :

This command gets the device state (stored in its device_state data member) and returns it to the caller.

State Definition		
Input Argument	Tango::DEV_VOID	none
Output Argument	Tango::DEV_STATE	Device state
DisplayLevel	OPERATOR	..
Inherited	true	..
Abstract	true	..
Polling Period	Not polled	..
Command allowed for	All states	..

Command Status :

This command gets the device status (stored in its device_status data member) and returns it to the caller.

Status Definition		
Input Argument	Tango::DEV_VOID	none
Output Argument	Tango::CONST_DEV_STRING	Device status
DisplayLevel	OPERATOR	..
Inherited	true	..
Abstract	true	..
Polling Period	Not polled	..
Command allowed for	All states	..

Command StartCtrlLoop :

Start control loop

StartCtrlLoop Definition		
Input Argument	Tango::DEV_VOID	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..

Abstract	false	..
Polling Period	Not polled	..
Command allowed for	All states	..

Command StopCtrlLoop :

Stop control loop

StopCtrlLoop Definition		
Input Argument	Tango::DEV_VOID	
Output Argument	Tango::DEV_VOID	
DisplayLevel	OPERATOR	..
Inherited	false	..
Abstract	false	..
Polling Period	Not polled	..
Command allowed for	All states	..

PIDController Class Attributes							
Name	Inherited	Abstract	Attr. type	R/W type	Data type	Level	Description
Proportional	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	P parameter
Integral	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	I parameter
Differential	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	D parameter
LoopTime	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	Cycle time for the control loop.
StartOutputValue	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	Start value for the output.
							Value readout from the input device

InputValue	false	false	Scalar	READ	Tango::DEV_DOUBLE	OPERATOR	or calculated from values from the input device Value
OutputValue	false	false	Scalar	READ	Tango::DEV_DOUBLE	OPERATOR	calculated by the PID controller and sent to the output device
OutputLimit	false	false	Scalar	READ_WRITE	Tango::DEV_DOUBLE	OPERATOR	Limit for the output value.

There is no dynamic attribute defined.

Attribute Proportional :

P parameter

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user	

code	false
Push DataReady event by user code	false

Attribute Integral :

I parameter

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute Differential :

D parameter

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute LoopTime :

Cicle time for the control loop.

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true

Attribute Properties	
label	
unit	s
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set

Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute StartOutputValue :

Start value for the output.

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed for	All states

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute InputValue :

Value readout from the input device or calculated from values from the input device

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	Not set
Read allowed for	All states

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute OutputValue :

Value calculated by the PID controller and sent to the output device

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ

Attribute Properties	
label	
unit	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not

Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	Not set
Read allowed for	All states

standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false
Push Archive event by user code	false
Push DataReady event by user code	false

Attribute OutputLimit :

Limit for the output value.

Attribute Definition	
Attribute Type	Scalar
R/W Type	READ_WRITE
Data Type	Tango::DEV_DOUBLE
Display Level	OPERATOR
Inherited	false
Abstract	false
Polling Period	Not polled
Memorized	true
Write hardware at init.	true
Read allowed for	All states
Write allowed	All states

Attribute Properties	
label	
unit	
standard unit	
display unit	
format	
max_value	
min_value	
max_alarm	
min_alarm	
max_warning	
min_warning	
delta_time	
delta_val	

Attribute Event Criteria	
Periodic	Not set
Relative Change	Not set
Absolute Change	Not set
Archive Periodic	Not set
Archive Relative Change	Not set
Archive Absolute Change	Not set
Push Change event by user code	false

for _____

Push Archive event by user code	false
Push DataReady event by user code	false

PIDController Class States	
Name	Description
ON	
MOVING	Control Loop is running
FAULT	